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Stochastic Control in Market Making

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Stochastic Control Problem

• state process
$$X = (X_t)_{t \in T}$$
;



- have control \(\alpha_t\) exert to the trajectory of \(X\)
- then we get the controlled diffusion process X

$$\mathrm{d}X_t = b(X_t, \alpha_t)\mathrm{d}t + \sigma(X_t, \alpha_t)\mathrm{d}W_t, X_0 = x \in \mathcal{R}^n$$

, where W_t is d-dimensional BM, control process α_t lying on control set $A \subset \mathcal{R}^m$. $b : \mathcal{R}^n \times A \mapsto \mathcal{R}^n, \sigma : \mathcal{R}^n \times A \mapsto \mathcal{R}^{n \times d}$

Finite Horizon Objective:

$$J(x;\alpha) := \mathbf{E}[\int_0^T f(t, X_t, \alpha_t) \mathrm{d}t + F(X_T)]$$

Value Function:

$$u := \sup_{\alpha \in A} J(x; \alpha)$$

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Market Making Basics



Definitions

- Market Orders (MO)
- Limit Orders (LO): Passive Quoting, resting on book
- Limit Order Book (LOB): Has bid and ask side, consisting of LOs
- Mid Price: Avg of Bid and Ask Price
- Spread: the difference between ask and bid
- Market Maker (MM): Market Maker quoting on both bid and ask side, providing liquidity to the market and charging the spread
 - MM wants to minize risk while maximize the profit.

Into the Market I





Figure: Well known MMs

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Into the Market II





Figure: A trading infra with Bid and Ask

Into the Market III



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Figure: DV Trading



Market Making Problem I



Mid Price Process S_t

$$S_t = S_0 + \sigma W_t$$

- ▶ MM posting depth: δ^{\pm} , LO on bid side: $S \delta^{-}$, on ask side: $S + \delta^+$
- MO Arrival Counting Process: $M^{\pm} \sim Pois(\lambda^{\pm})$
- ▶ LO filling Counting Process: $N^{\pm} \sim Exp(\kappa^{\pm})$:

$$\mathrm{d}N^{\pm} = \exp(-\kappa^{\pm}\delta_t^{\pm})\mathrm{d}M^{\pm}$$

MM Cash Process:

$$\mathrm{d}X_t^{\delta} = (S_{t^-} + \delta_t^+)\mathrm{d}N_t^{\delta,+} - (S_{t^-} - \delta_t^-)\mathrm{d}N_t^{\delta,-}$$

Market Making Problem II



▶ Inventory Process: $Q_t^{\delta} = N_t^{\delta,-} - N_t^{\delta,+}$

MM's performance:

$$H^{\delta}(t,x,S,q) = \mathbf{E}_{t,x,S,q}[X_{T} + Q_{T}(S_{T} - \alpha Q_{T}) - \phi \int_{t}^{T} (Q_{u})^{2} d_{u}]$$

Objective:

$$H(t, x, S, q) = \sup_{\delta^{\pm}} H^{\delta}(t, x, S, q)$$

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The MM use random control δ during $[t, t + \epsilon)$ • The MM use optimal control $\hat{\delta}$ during $[t + \epsilon, T]$ Then we obtain the following inequality

$$H(t, x, S, q) \ge E[-\int_{t}^{t+\epsilon} Q_{u}^{2} \mathrm{d}u + H(t+\epsilon, x_{t+\epsilon}, S_{t+\epsilon}, q_{t+\epsilon})] \quad (1)$$



$$H(t + \epsilon, x_{t+\epsilon}, S_{t+\epsilon}, q_{t+\epsilon}) = H(t, x, S, q)$$

$$+ \int_{t}^{t+\epsilon} \partial_{t}H + \frac{\sigma^{2}}{2} \partial_{SS}Hdu + \int_{t}^{t+\epsilon} \sigma \partial_{S}HdW_{u}$$

$$+ \int_{t}^{t+\epsilon} (H(u, x + (S + \delta^{+}), S, q - 1) - H)dN^{\delta, +}$$

$$+ \int_{t}^{t+\epsilon} (H(u, x - (S - \delta^{-}), S, q + 1) - H)dN^{\delta, -}$$
(2)

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Inject back to Eqn(1), take the sup we get:

$$0 = \partial_t H + \frac{1}{2} \sigma^2 \partial_{SS} H - \phi q^2 + \lambda^+ \sup_{\delta^+} [e^{-\kappa^+ \delta^+} (H(t, x + (S + \delta^+), q - 1, S) - H)]$$
(3)
+ $\lambda^+ \sup_{\delta^-} [e^{-\kappa^- \delta^-} (H(t, x - (S - \delta^-), q + 1, S) - H)]$

with the terminal condition:

$$H(T, x, S, q) = x + q(S - \alpha q)$$

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Optimal Controls



For the following ansatz for ${\boldsymbol{H}}$

$$H(t, x, q, S) = x + qS + h(t, q)$$

We have optimal controls:

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$$\delta^+=rac{1}{\kappa^+}-h(t,q-1)+h(t,q)$$

and

$$\delta^-=\frac{1}{\kappa^-}-h(t,q+1)+h(t,q)$$

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Property of the Solution, $\phi = 0.01$





Figure: The optimal depths as a function of time for various inventory levels and T = 30. The remaining model parameters are: $\lambda^{\pm} = 1$, $\kappa^{\pm} = 100$, $\overline{q} = -\underline{q} = 3$, $\phi = 0.001$ and $\phi = 0.02$, $\alpha = 0.0001$, $\sigma = 0.01$, $S_0 = 100$.

Figure: Solution, credit to Prof. Jan Obloj

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Property of the Solution, $\phi = 0.02$





Figure: The optimal depths as a function of time for various inventory levels and T = 30. The remaining model parameters are: $\lambda^{\pm} = 1$, $\kappa^{\pm} = 100$, $\overline{q} = -\underline{q} = 3$, $\phi = 0.001$ and $\phi = 0.02$, $\alpha = 0.0001$, $\sigma = 0.01$, $S_0 = 100$.

Figure: Solution, credit to Prof. Jan Obloj

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 Stochastic Control in Market Making

Drawbacks & Frontiers



- Mid Price is not a good measure
 - Fair Price which measures instruments correlation
- Fair Price is hard to formulate
 - Incorporate Alpha signals into Price Formulation
- No Aggressive Fill possibility
- Hawkes Process instead of Poisson Process
- Poor Property leads to numerical solution, while solving high dimensional PDE is time-consuming

Jane Street sue LME

US trading firm Jane Street sues LME for nickel trade chaos

Lawsuit comes a day after similar action by Elliott against metals exchange over March trade halt



William Langley in Hong Kong JUNE 7 2022

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Jane Street, a top Wall Street market maker, has followed US hedge fund Elliott Management and launched a lawsuit against the London Metal Exchange over the nickel short squeeze fiasco.

Figure: Jane Street Sue London Metal Exchange

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